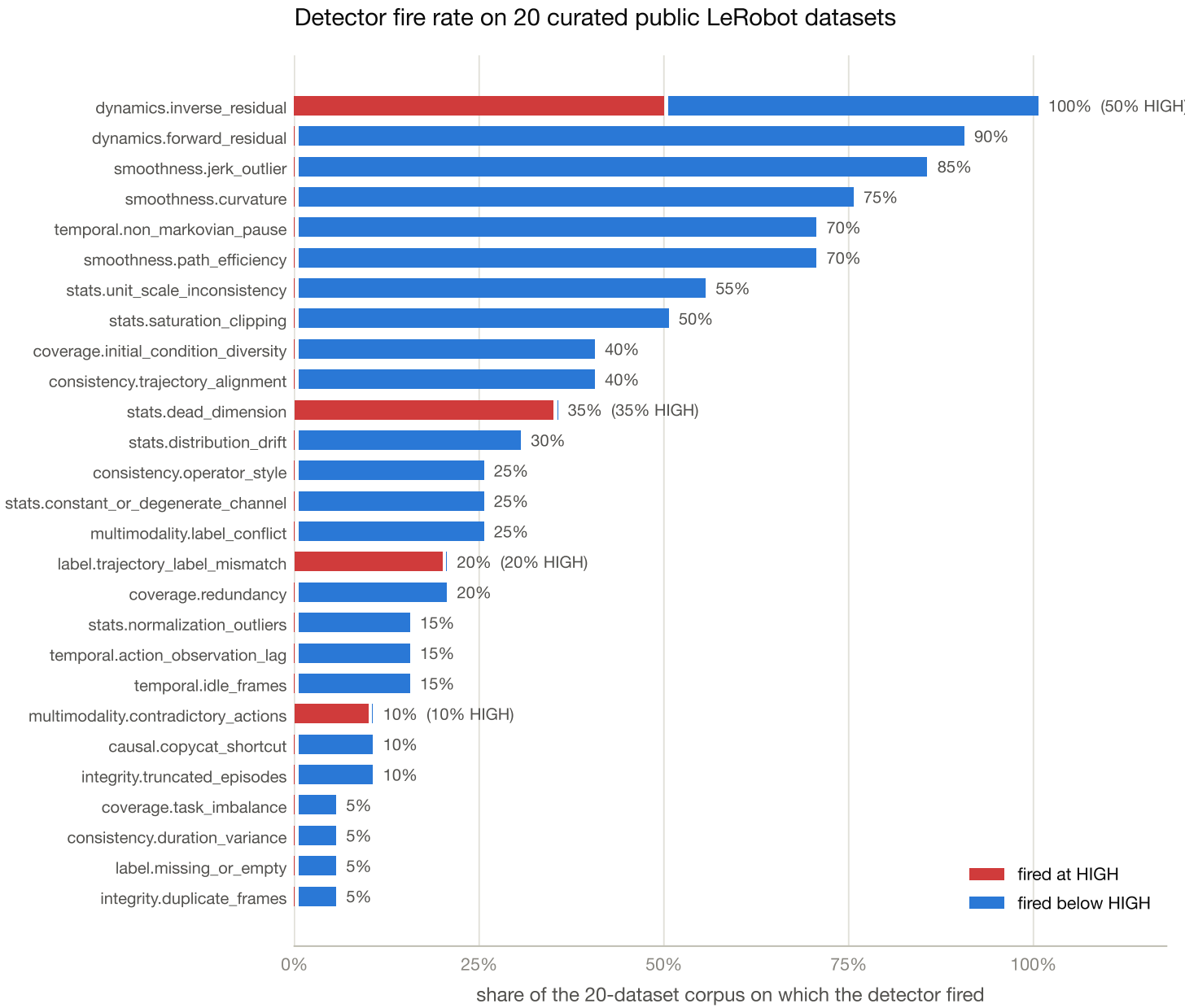
Detector fire rate on 20 curated public LeRobot datasets
dynamics.inverse_residual
dynamics.forward_residual
smoothness.jerk_outlier
smoothness.curvature
temporal.non_markovian_pause
smoothness.path_efficiency
stats.unit_scale_inconsistency
stats.saturation_clipping
coverage.initial_condition_diversity
consistency.trajectory_alignment
stats.dead_dimension
stats.distribution_drift
consistency.operator_style
stats.constant_or_degenerate_channel
multimodality.label_conflict
label.trajectory_label_mismatch
coverage.redundancy
stats.normalization_outliers
temporal.action_observation_lag
temporal.idle_frames
multimodality.contradictory_actions
causal.copycat_shortcut
integrity.truncated_episodes
coverage.task_imbalance
consistency.duration_variance
label.missing_or_empty
integrity.duplicate_frames
100% (50% HIGH)
90%
85%
75%
70%
70%
55%
50%
40%
40%
35% (35% HIGH)
30%
25%
25%
25%
20% (20% HIGH)
20%
15%
15%
15%
10% (10% HIGH)
10%
10%
5%
5%
5%
5%
fired at HIGH
fired below HIGH
0%
25%
50%
75%
100%
share of the 20-dataset corpus on which the detector fired