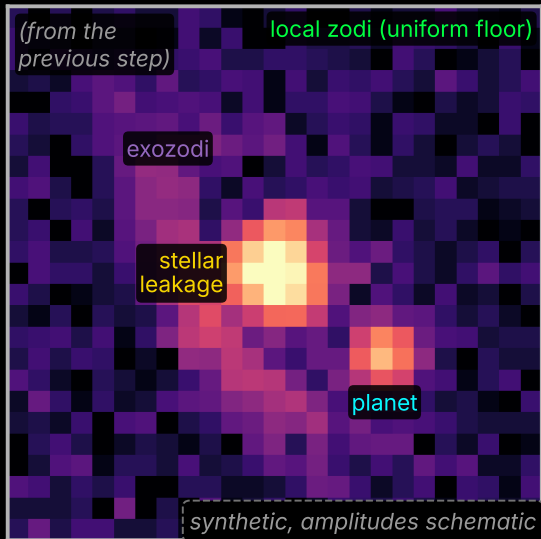


Each visit reduces to one record

raw frame, one visit



the record of visit k

epoch t_k

detected? D_k

which calibration

if reported:

east, north offsets (ξ_k, η_k)

their uncertainty C_k