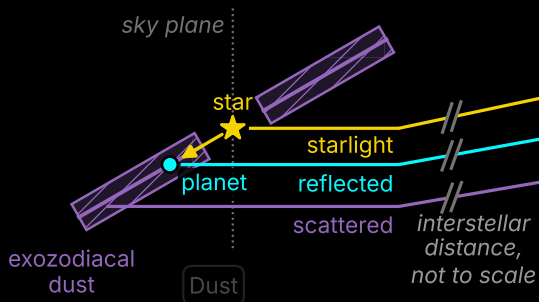


Geometry

target system, side view
observer to the right

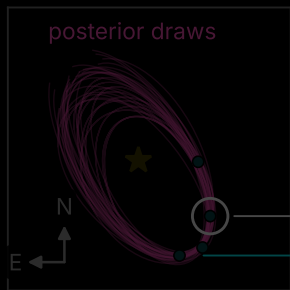
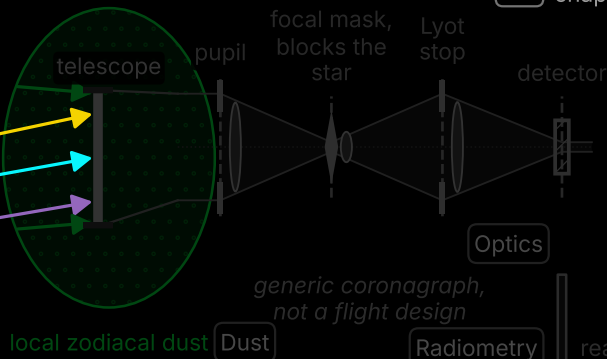


→ light, propagating
→ data, transformed

schematic of the simulation scope, not to scale

□ chapter that defines it

□ **this chapter**



infer with
an assumed
model

current visit
measured

Records
epoch t_k
detected? D_k
which calibration
if reported:
east, north offsets (ξ_k, η_k)
their uncertainty C_k

records, one per visit

reduce



raw frame, synthetic